



# Piecewise linear process with renewal starting points

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## ABSTRACT

This paper concerns a Markovian piecewise linear process, based on a continuous-time Markov chain with a finite state space. The process describes the movement of a particle that takes a new linear trend starting from a new random point (with state-dependent distribution) after each trend switch. The distribution of particle's position is derived in a closed form. In some special cases the distributions of the level passage times are provided explicitly.

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## 1. Introduction and main definitions

Let  $\varepsilon = \varepsilon(t)$ ,  $t \geq 0$ , be a continuous-time homogeneous Markov chain with the finite state space  $E$ . Let  $\Phi(t) = e^{t\Lambda} = (\Phi_{ij}(t))_{i,j \in E}$  be the transition semi-group with the infinitesimal generator  $\Lambda$ . Consider the sequence of switching times,  $0 < T_1 < T_2 < \dots < T_n < \dots$ ,  $T_0 = 0$ , and denote by  $N(t)$  the number of switchings occurred up to time  $t$ ,  $N(t) = \max\{n \mid T_n \leq t\}$ .

We study the piecewise linear random process

$$X(t) = x_{N(t)} + c_{\varepsilon(T_{N(t)})}(t - T_{N(t)}), \quad t \geq 0. \tag{1.1}$$

Here  $c_i$ ,  $i \in E$ , are deterministic constants, and  $x_n$ ,  $n \geq 0$ , are independent random variables with distributions determined by the current state  $\varepsilon(T_n)$ .

Process  $X(t)$ ,  $t \geq 0$ , describes the location of a particle that moves linearly and takes a new starting point after each trend switch. Process  $X$  resembles well-studied Markovian growth-collapse processes, see e.g. Boxma et al. (2006). In contrast with (1.1) the growth-collapse processes presume a constant trend with additive or multiplicative *down* jumps. Such models occur in insurance mathematics and related fields, see Asmussen (2003, XIV-5) or Rolski et al. (1999, Chapters 5 and 11), and in production/inventory models studied by Shanthikumar and Sumita (1983), among others.

On the other hand, (1.1) is related to jump-telegraph process  $\mathbb{T}(t) := \int_0^t c_{\varepsilon(u)} du + \int_0^t Y_{\varepsilon(u-)} dN_u$ , which is a piecewise linear process jumping from the current position, see e.g. Di Crescenzo et al. (2013) and López and Ratanov (2012); piecewise linear processes with jumps are presented by Ratanov (2014). Jump-telegraph processes are widely applied in various fields, including financial market modelling, see Kolesnik and Ratanov (2013).

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In contrast to jump-telegraph process,  $X(t)$ ,  $t \geq 0$ , (1.1), completely updates starting points. Possible applications of this type of processes could be in financial modelling and insurance mathematics.

The paper is structured as follows. In Section 2 we give explicit formulae for transition densities, expectations and limit distributions of  $X(t)$  (as  $t \rightarrow \infty$ ). Section 3 is devoted to a detailed analysis of the level passage times in the case of the two-state underlying Markov process  $\varepsilon$ .

**2. Distribution**

Define the transition probabilities  $\mathbf{p}(t, dy | x)$  and  $\mathbf{p}(t, dy)$  by entries

$$p_i(t, dy | x) = \mathbb{P}\{X(t) \in dy | \varepsilon(0) = i, X(0) = x\}, \quad -\infty < x, y < \infty, \tag{2.1}$$

and

$$p_i(t, dy) = \int_{-\infty}^{\infty} p_i(t, dy | x)g_i(dx), \quad -\infty < y < \infty, \quad i \in E, \tag{2.2}$$

where  $g_i(dx)$  is the distribution of the initial starting point at the initial state  $i = \varepsilon(0)$ . By conditioning on the first switching one can obtain the following integral equations

$$p_i(t, dy | x) = e^{-\lambda_i t} \delta_{x+c_i t}(dy) + \sum_{j \in E, j \neq i} \int_0^t \lambda_{ij} e^{-\lambda_i \tau} p_j(t - \tau, dy) d\tau, \quad i \in E, \tag{2.3}$$

where  $\delta_a(dy)$  denotes  $\delta$ -measure localised at point  $a$  and  $\lambda_i = \sum_{j \in E, j \neq i} \lambda_{ij}$ . Further, by (2.2)

$$p_i(t, dy) = e^{-\lambda_i t} g_i^{tc_i}(dy) + \sum_{j \in E, j \neq i} \int_0^t \lambda_{ij} e^{-\lambda_i \tau} p_j(t - \tau, dy) d\tau, \quad i \in E. \tag{2.4}$$

Here  $g_i^a(dy)$  is the displacement of measure  $g_i$ : for any integrable test-function  $\phi$

$$\int_{-\infty}^{\infty} \phi(y) g_i^a(dy) = \int_{-\infty}^{\infty} \phi(y + a) g_i(dy).$$

Systems (2.3) and (2.4) can be solved explicitly. Note that when all trends vanish,  $c_i = 0$ ,  $i \in E$ , the distribution of  $X(t) = x_{N(t)}$  is given by  $\mathbb{P}\{X(t) \in dx | \varepsilon(0) = i\} = \sum_{j \in E} \Phi_{ij}(t) g_j(dx)$ , where  $\Phi_{ij}(t)$  are the entries of the transition semi-group  $e^{t\Lambda}$  introduced in Section 1.

**Theorem 2.1.** *The transition probabilities  $\mathbf{p}(t, dy | x)$  and  $\mathbf{p}(t, dy)$ , (2.1)–(2.2), have the form*

$$p_i(t, dy | x) = e^{-\lambda_i t} \delta_{x+tc_i}(dy) + \sum_{j \in E} \int_0^t \Phi_{ij}(t - \tau) \left[ \sum_{k \in E, k \neq j} \lambda_{jk} e^{-\lambda_k \tau} g_k^{tc_k}(dy) \right] d\tau, \tag{2.5}$$

$$p_i(t, dy) = e^{-\lambda_i t} g_i^{tc_i}(dy) + \sum_{j \in E} \int_0^t \Phi_{ij}(t - \tau) \left[ \sum_{k \in E, k \neq j} \lambda_{jk} e^{-\lambda_k \tau} g_k^{tc_k}(dy) \right] d\tau, \quad i \in E. \tag{2.6}$$

Let

$$M_i(t) = \int_{-\infty}^{\infty} \mathbb{E} \{X_i(t) | \varepsilon(0) = i, X_i(0) = x\} g_i(dx), \quad i \in E.$$

Then,

$$M_i(t) = e^{-\lambda_i t} (m_i + tc_i) + \sum_{j \in E} \int_0^t \Phi_{ij}(t - \tau) \left[ \sum_{k \in E, k \neq j} \lambda_{jk} e^{-\lambda_k \tau} (m_k + \tau c_k) \right] d\tau, \tag{2.7}$$

where  $m_i = \int_{-\infty}^{\infty} x g_i(dx)$ ,  $i \in E$ .

**Proof.** By conditioning on the last switching time and using the time-reversal property, see e.g. Brémaud (1999), one can derive (2.5): the first term corresponds to the case of no switchings and other summands describe the movement of the particle, which starts at time 0 from the state  $i \in E$  and makes the last switching at time  $t - \tau$ . Eq. (2.6) follows from (2.2). Formula (2.7) follows from (2.6). □

**Example 2.1.** Let  $c_i = 1$ ,  $\lambda_i = \lambda$ ,  $i \in E$ , and the random points  $x_n$  are identically distributed with distribution  $g$ . In this case (2.6) becomes

$$p(t, dy) = e^{-\lambda t} g^t(dy) + \int_0^t \lambda e^{-\lambda \tau} g^\tau(dy) d\tau. \tag{2.8}$$

After applying Fubini’s theorem one can see that the distribution (2.8) of  $X(t)$  is

$$p(t, dy) = e^{-\lambda t} g^t(dy) + \left[ \lambda e^{-\lambda y} \int_{y-t}^y e^{\lambda x} g(dx) \right] dy. \tag{2.9}$$

In particular, if  $g(dy) = \delta(dy)$ , that is  $x_n = 0$   $n \geq 0$ , then by (2.9)

$$p(t, dy) = e^{-\lambda t} \delta_t(dy) + \lambda e^{-\lambda y} \mathbb{1}_{0 < y < t} dy. \tag{2.10}$$

**Example 2.2.** Consider the two-state Markov chain with alternating switching intensities  $\lambda_0, \lambda_1$ , so called flip-flop process, Brémaud, (1999). Let  $2\lambda = \lambda_0 + \lambda_1$  and  $2\nu = \lambda_0 - \lambda_1$ . The transition semi-group is defined by

$$\Phi(t) = \exp(tA) = \frac{1}{2\lambda} \begin{pmatrix} \lambda_1 + \lambda_0 e^{-2\lambda t} & \lambda_0 (1 - e^{-2\lambda t}) \\ \lambda_1 (1 - e^{-2\lambda t}) & \lambda_0 + \lambda_1 e^{-2\lambda t} \end{pmatrix},$$

see e.g. Kolesnik and Ratanov (2013, 4.1.23).

In this case formula (2.6) becomes

$$\mathbf{p}(t, dy) = e^{-tA^{\text{diag}}} \mathbf{g}^t \mathbf{c}(dy) + \lambda_0 \lambda_1 \int_0^t A(t - \tau) e^{-\tau A^{\text{diag}}} [\mathbf{g}^{\tau \mathbf{c}}(dy)] d\tau, \tag{2.11}$$

where

$$A^{\text{diag}} = \begin{pmatrix} \lambda_0 & 0 \\ 0 & \lambda_1 \end{pmatrix}$$

and

$$A(t) = e^{-\lambda t} \begin{pmatrix} \lambda^{-1} \sinh(\lambda t) & \lambda_1^{-1} \left( \cosh(\lambda t) - \frac{\nu}{\lambda} \sinh(\lambda t) \right) \\ \lambda_0^{-1} \left( \cosh(\lambda t) + \frac{\nu}{\lambda} \sinh(\lambda t) \right) & \lambda^{-1} \sinh(\lambda t) \end{pmatrix}. \tag{2.12}$$

Note, that in the case  $\lambda_0 = \lambda_1 = \lambda$  and  $g_0 = g_1 = g$  formula (2.11) coincides with (2.9).

In the two-state case formula (2.7) for expectations can be simplified also. Let  $\mathbf{M} = (M_0, M_1)$ . By (2.11) we have

$$\mathbf{M}(t) = e^{-tA^{\text{diag}}} (\mathbf{m} + t\mathbf{c}) + \lambda_0 \lambda_1 \int_0^t A(t - \tau) e^{-\tau A^{\text{diag}}} (\mathbf{m} + \tau \mathbf{c}) d\tau, \tag{2.13}$$

where  $\mathbf{c} = (c_0, c_1)'$  and  $\mathbf{m} = (m_0, m_1)'$ . Formula (2.13) can be expressed explicitly, but this is tedious. If  $\lambda_0 = \lambda_1 = \lambda > 0$ , this formula looks simpler:

$$\mathbf{M}(t) = \mathbf{m} + \frac{1 - e^{-\lambda t}}{\lambda} \begin{pmatrix} c_1 \\ c_0 \end{pmatrix} + \frac{1 - e^{-2\lambda t}}{2\lambda} \begin{pmatrix} \Delta c - \lambda \Delta m \\ \lambda \Delta m - \Delta c \end{pmatrix}, \tag{2.14}$$

where  $\Delta c = c_0 - c_1$ ,  $\Delta m = m_0 - m_1$ .

To prove (2.14) first note that in this case formula (2.13) becomes

$$\mathbf{M}(t) = e^{-\lambda t} (\mathbf{m} + t\mathbf{c}) + \lambda^2 \int_0^t e^{-\lambda \tau} A(t - \tau) (\mathbf{m} + \tau \mathbf{c}) d\tau,$$

where

$$A(t) = \frac{1}{2\lambda} \begin{pmatrix} 1 - e^{-2\lambda t} & 1 + e^{-2\lambda t} \\ 1 + e^{-2\lambda t} & 1 - e^{-2\lambda t} \end{pmatrix},$$

such that

$$A(0) = \frac{1}{\lambda} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{and} \quad \frac{dA(t)}{dt} = e^{-2\lambda t} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}.$$

Therefore,

$$\frac{d\mathbf{M}(t)}{dt} = e^{-\lambda t} \begin{pmatrix} c_0 - \lambda(\Delta m + t\Delta c) \\ c_1 + \lambda(\Delta m + t\Delta c) \end{pmatrix} + \lambda^2 e^{-2\lambda t} \int_0^t e^{\lambda \tau} \begin{pmatrix} \Delta m + \tau \Delta c \\ -\Delta m - \tau \Delta c \end{pmatrix} d\tau.$$

By integrating we have

$$\begin{aligned} \frac{d\mathbf{M}(t)}{dt} &= e^{-\lambda t} \mathbf{c} - \lambda e^{-2\lambda t} \begin{pmatrix} \Delta m \\ -\Delta m \end{pmatrix} - (e^{-\lambda t} - e^{-2\lambda t}) \begin{pmatrix} \Delta c \\ -\Delta c \end{pmatrix} \\ &= e^{-\lambda t} \begin{pmatrix} c_1 \\ c_0 \end{pmatrix} + e^{-2\lambda t} \begin{pmatrix} \Delta c - \lambda \Delta m \\ \lambda \Delta m - \Delta c \end{pmatrix}, \end{aligned}$$

which gives (2.14).

From Theorem 2.1 one can obtain the limiting distribution, as  $t \rightarrow \infty$ .

Let  $\varepsilon = \varepsilon(t)$  be an ergodic regular homogeneous Markov chain, Brémaud, (1999), that is

$$\lim_{t \rightarrow \infty} \Phi_{ij}(t) = \pi_j, \quad i, j \in E. \tag{2.15}$$

**Theorem 2.2.** Process  $X(t)$  converges in distribution, as  $t \rightarrow \infty$ . The limit distribution is

$$\bar{p}(dy) = \sum_{j, k \in E, k \neq j} \pi_j \lambda_{jk} \psi_k(\lambda_k, dy), \tag{2.16}$$

where  $\psi_k(s, \cdot) = \int_0^\infty e^{-s\tau} g_k^{\tau c_k}(\cdot) d\tau$  is the time-Laplace transform of distribution  $g_k^{tc_k}(\cdot)$ .

The limit of expectations is given by

$$\lim_{t \rightarrow \infty} M_i(t) = \sum_{j \in E} \pi_j \sum_{k \in E, k \neq j} \left( m_k + \frac{c_k}{\lambda_k} \right) \frac{\lambda_{jk}}{\lambda_k}, \quad i \in E. \tag{2.17}$$

**Proof.** Applying (2.15) to (2.6) by Lebesgue's dominated convergence theorem we obtain

$$\lim_{t \rightarrow \infty} p_i(t, dy) = \sum_{j \in E} \pi_j \sum_{k \in E, k \neq j} \lambda_{jk} \int_0^\infty e^{-\lambda_k \tau} g_k^{\tau c_k}(dy) d\tau, \tag{2.18}$$

which gives (2.16).

By (2.7)

$$\lim_{t \rightarrow \infty} M_i(t) = \sum_{j, k \in E, j \neq k} \pi_j \lambda_{jk} \int_0^\infty e^{-\lambda_k \tau} (m_k + \tau c_k) d\tau,$$

which gives (2.17).  $\square$

Formula (2.16) looks in detail as

$$\begin{aligned} \bar{p}(dy) &= \sum_{j, k \in E, k \neq j} \frac{\pi_j \lambda_{jk}}{|c_k|} e^{-\lambda_k y / c_k} \left[ \int_{-\infty}^y e^{\lambda_k z / c_k} g_k(dz) \mathbb{1}_{\{c_k > 0\}} + \int_y^\infty e^{\lambda_k z / c_k} g_k(dz) \mathbb{1}_{\{c_k < 0\}} \right] dy \\ &\quad + \sum_{j, k \in E, k \neq j} \pi_j \frac{\lambda_{jk}}{\lambda_k} g_k(dy) \mathbb{1}_{\{c_k = 0\}}. \end{aligned} \tag{2.19}$$

To prove this, note that with any test-function  $\phi$  applied to the integral term of (2.18) we have

$$\int_{-\infty}^\infty \phi(y) \int_0^\infty e^{-\lambda_k \tau} g_k^{\tau c_k}(dy) d\tau = \int_{-\infty}^\infty \left[ \int_0^\infty \phi(y + c_k \tau) e^{-\lambda_k \tau} d\tau \right] g_k(dy).$$

By applying again Fubini's theorem we obtain

$$\frac{1}{c_k} \int_{-\infty}^\infty \phi(y) e^{-\lambda_k y / c_k} \left[ \int_{-\infty}^y e^{\lambda_k z / c_k} g_k(dz) \right] dy, \quad \text{if } c_k > 0;$$

$$\frac{1}{|c_k|} \int_{-\infty}^\infty \phi(y) \left[ e^{-\lambda_k y / c_k} \int_y^\infty e^{\lambda_k z / c_k} g_k(dz) \right] dy, \quad \text{if } c_k < 0;$$

and

$$\frac{1}{\lambda_k} \int_{-\infty}^\infty \phi(y) g_k(dy), \quad \text{if } c_k = 0.$$

**Example 2.2** (continued). Note that in the case of Example 2.2 the limiting distribution (2.19) can be simplified to

$$\bar{p}(dy) = \frac{\lambda_0 \lambda_1}{2\lambda} [\psi_0(\lambda_0, dy) + \psi_1(\lambda_1, dy)], \tag{2.20}$$

and formula (2.17) becomes

$$\lim_{t \rightarrow \infty} M_0(t) = \lim_{t \rightarrow \infty} M_1(t) = \frac{\lambda_0 \lambda_1}{2\lambda} \left[ \frac{m_0}{\lambda_0} + \frac{m_1}{\lambda_1} + \frac{c_0}{\lambda_0^2} + \frac{c_1}{\lambda_1^2} \right].$$

### 3. First passage time

Let  $T_i^x = T_i^x(y) = \inf\{t > 0 : X_i(t) \geq y\}$ , be the first passage time through the fixed level  $y$  starting with the initial point  $x$ ,  $X_i(0) = x < y$ ;  $\varepsilon(0) = i \in E$ . To avoid overshooting we assume that the distributions of  $x_n$  are supported in  $(-\infty, y)$ . From viewpoint of possible applications, this means that the supporting level  $y$  is visible for a moving particle.

If all velocities are nonpositive,  $c_j \leq 0$ ,  $j \in E$ , then  $T_j^x(y) = \infty$ , a.s. Note that in the case of a positive velocity  $c_i$  the distribution of  $T_i^x(y)$  has an atom: if  $c_i > 0$ , then  $\mathbb{P}\{T_i^x(y) = (y - x)/c_i\} = \exp(-\lambda_i(y - x)/c_i)$ .

Let  $f_i(x, y, t)$  be the density function of  $T_i^x(y)$ ,

$$f_i(x, y, t) := \mathbb{P}\{T_i^x(y) \in dt\}/dt, \quad t > 0, \quad i \in E.$$

Conditioning on the first switching we obtain

$$\begin{aligned} f_i(x, y, t) = & e^{-\lambda_i \xi_i} \delta(t - \xi_i) + \sum_{\substack{j \in E, j \neq i \\ c_j > 0}} \int_0^{t \wedge \xi_i} \lambda_{ij} e^{-\lambda_j \tau} \left[ \int_{-\infty}^{\infty} f_j(z, y, t) g_j(dz) \right] d\tau \\ & + \sum_{\substack{j \in E, j \neq i \\ c_j \leq 0}} \int_0^t \lambda_{ij} e^{-\lambda_j \tau} \left[ \int_{-\infty}^{\infty} f_j(z, y, t) g_j(dz) \right] d\tau, \quad i \in E, \end{aligned} \quad (3.1)$$

where  $\delta(\cdot)$  is Dirac's  $\delta$ -function and  $\xi_i = (y - x)/c_i$ .

In what follows we study in detail the "flip-flop" case of the two-state Markov process  $\varepsilon$ ,  $\varepsilon(t) \in E = \{0, 1\}$ .

#### 3.1. Positive velocities

Let both trends be positive,  $c_0 \geq c_1 > 0$ , and the alternating distributions  $g_0, g_1$  of renewal starting points satisfy the condition  $g_i((-\infty, y)) = 1$ ,  $i \in \{0, 1\}$ .

**Theorem 3.1.** *The first passage times  $T_0^x$  and  $T_1^x$  have proper distributions,*

$$\mathbb{P}\{T_0^x(y) < \infty\} = \mathbb{P}\{T_1^x(y) < \infty\} = 1, \quad x < y. \quad (3.2)$$

Let the renewal starting points be exponentially distributed over the half-line  $(-\infty, y)$ ,

$$g_i(dz) = a_i \exp(-a_i(y - z)) \mathbb{1}_{\{z < y\}} dz, \quad a_i > 0,$$

and  $\mu_i = \lambda_i + c_i a_i$ ,  $i \in \{0, 1\}$ . Then, the density functions  $f_0$  and  $f_1$  are given by

$$f_i(x, y, t) = e^{-\lambda_i \xi_i} \delta(t - \xi_i) + \lambda_i \left[ A_{1-i} u(t \wedge \xi_i, \lambda_i - s_0^*) e^{-s_0^* t} + B_{1-i} u(t \wedge \xi_i, \lambda_i - s_1^*) e^{-s_1^* t} \right], \quad i \in \{0, 1\}. \quad (3.3)$$

Here

$$\xi_i := \frac{y - x}{c_i}, \quad s_0^* = \frac{\mu_0 + \mu_1 - \sqrt{D}}{2}, \quad s_1^* = \frac{\mu_0 + \mu_1 + \sqrt{D}}{2}, \quad (3.4)$$

$D = (\mu_0 - \mu_1)^2 + 4\lambda_0 \lambda_1$ ; constants  $A_i$  and  $B_i$  are given by

$$A_0 = \frac{\mu_0 \mu_1 - \lambda_0 \lambda_1 - (\mu_0 - \lambda_0) s_0^*}{\sqrt{D}}, \quad B_0 = \frac{\lambda_0 \lambda_1 - \mu_0 \mu_1 + (\mu_0 - \lambda_0) s_1^*}{\sqrt{D}}, \quad (3.5)$$

$$A_1 = \frac{\mu_0 \mu_1 - \lambda_0 \lambda_1 - (\mu_1 - \lambda_1) s_0^*}{\sqrt{D}}, \quad B_1 = \frac{\lambda_0 \lambda_1 - \mu_0 \mu_1 + (\mu_1 - \lambda_1) s_1^*}{\sqrt{D}}, \quad (3.6)$$

and

$$u(\xi, \beta) := \int_0^\xi e^{-\beta \tau} d\tau = \begin{cases} \frac{1 - e^{-\beta \xi}}{\beta}, & \beta \neq 0, \\ \xi, & \beta = 0. \end{cases} \quad (3.7)$$

**Proof.** For the two-state case, by (3.1) the following coupled equations hold: for  $t > 0$

$$\begin{cases} f_0(x, y, t) = e^{-\lambda_0 \xi_0} \delta(t - \xi_0) + \int_0^{t \wedge \xi_0} \lambda_0 e^{-\lambda_0 \tau} h_1(y, t - \tau) d\tau, \\ f_1(x, y, t) = e^{-\lambda_1 \xi_1} \delta(t - \xi_1) + \int_0^{t \wedge \xi_1} \lambda_1 e^{-\lambda_1 \tau} h_0(y, t - \tau) d\tau, \end{cases} \tag{3.8}$$

where  $h_i(y, t) = [\mathcal{G}f_i](y, t) := \int_{-\infty}^{\infty} f_i(z, y, t) g_i(dz)$ ,  $i \in E = \{0, 1\}$ . Let

$$\alpha_i(y, s) = [\mathcal{L}_{t \rightarrow s} h_i](y, s) = [\mathcal{L}_{t \rightarrow s} (\mathcal{G}f_i)](y, s), \quad s \geq 0,$$

be the time-Laplace transform of  $h_i$ ,  $i \in \{0, 1\}$ .

By applying to system (3.8) the time-Laplace transformation  $\mathcal{L}_{t \rightarrow s}$  we have

$$\begin{cases} [\mathcal{L}_{t \rightarrow s} f_0](x, y, s) = \exp(-(\lambda_0 + s)\xi_0) + \lambda_0 u(\xi_0, \lambda_0 + s) \alpha_1(y, s), \\ [\mathcal{L}_{t \rightarrow s} f_1](x, y, s) = \exp(-(\lambda_1 + s)\xi_1) + \lambda_1 u(\xi_1, \lambda_1 + s) \alpha_0(y, s), \end{cases} \tag{3.9}$$

since

$$\mathcal{L}_{t \rightarrow s} \delta(t - \xi) = \exp(-s\xi)$$

and, by Fubini's theorem,

$$\begin{aligned} \mathcal{L}_{t \rightarrow s} \int_0^{t \wedge \xi} e^{-\lambda \tau} h(y, t - \tau) d\tau &= \int_0^{\infty} e^{-st} dt \int_0^{t \wedge \xi} e^{-\lambda \tau} h(y, t - \tau) d\tau \\ &= \int_0^{\xi} e^{-\lambda \tau} d\tau \int_{\tau}^{\infty} e^{-st} h(y, t - \tau) dt = u(\xi, \lambda + s) \alpha(y, s). \end{aligned}$$

Here function  $u = u(\xi, \beta)$  is defined by (3.7).

Note that  $\mathcal{L}_{t \rightarrow s}$  is commutative with  $\mathcal{G}_0$  and  $\mathcal{G}_1$ . Applying operator  $\mathcal{G}_0$  to the first equation of (3.9) and operator  $\mathcal{G}_1$  to the second one, we obtain the linear algebraic system,

$$\begin{cases} \alpha_0(y, s) = \hat{g}_0(\beta_0(s)) + \frac{\lambda_0}{\lambda_0 + s} [1 - \hat{g}_0(\beta_0(s))] \alpha_1(y, s), \\ \alpha_1(y, s) = \hat{g}_1(\beta_1(s)) + \frac{\lambda_1}{\lambda_1 + s} [1 - \hat{g}_1(\beta_1(s))] \alpha_0(y, s), \end{cases}$$

where  $\beta_0(s) = \frac{\lambda_0 + s}{c_0}$ ,  $\beta_1(s) = \frac{\lambda_1 + s}{c_1}$  and

$$\hat{g}_i(\beta) = \int_{-\infty}^{\infty} e^{-\beta(y-x)} g_i(dx), \quad \beta > 0, \quad i \in \{0, 1\}. \tag{3.10}$$

The integral in (3.10) converges by the condition,  $g_i([y, \infty)) = 0$ .

The solution of the algebraic system is given by

$$\begin{cases} \alpha_0(y, s) = (Q(s))^{-1} \left\{ \hat{g}_0(\beta_0(s)) + \frac{\lambda_0}{\lambda_0 + s} [1 - \hat{g}_0(\beta_0(s))] \hat{g}_1(\beta_1(s)) \right\}, \\ \alpha_1(y, s) = (Q(s))^{-1} \left\{ \hat{g}_1(\beta_1(s)) + \frac{\lambda_1}{\lambda_1 + s} \hat{g}_0(\beta_0(s)) [1 - \hat{g}_1(\beta_1(s))] \right\}, \end{cases} \tag{3.11}$$

where  $Q(s) = 1 - \frac{\lambda_0 \lambda_1}{(\lambda_0 + s)(\lambda_1 + s)} \left( 1 - \hat{g}_0\left(\frac{\lambda_0 + s}{c_0}\right) \right) \left( 1 - \hat{g}_1\left(\frac{\lambda_1 + s}{c_1}\right) \right)$ ,  $s > 0$ .

By (3.11) it is easy to see that  $\alpha_0(y, 0) = \alpha_1(y, 0) = 1$ . Therefore, due to (3.9) the first passage times  $T_0^x(y)$  and  $T_1^x(y)$  have proper distributions  $\mathbb{P}\{T_0^x(y) < \infty\} = \mathbb{P}\{T_1^x(y) < \infty\} = 1$ ,  $\forall y, y > x$ .

Functions  $\alpha_0(y, s)$  and  $\alpha_1(y, s)$  can be obtained explicitly whenever the renewal starting points are exponentially distributed over half-line  $(-\infty, y)$ ,

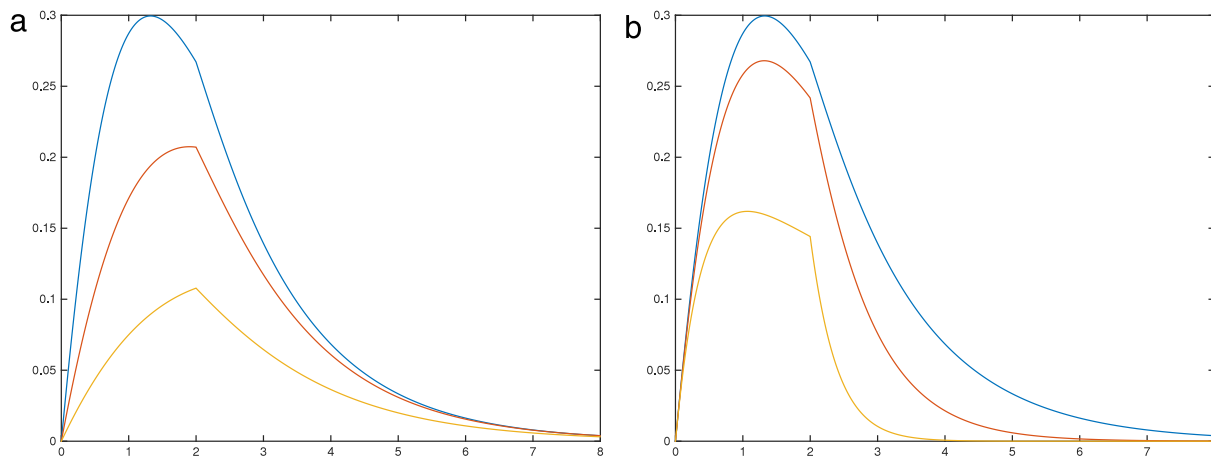
$$g_i(dz) = a_i \exp(-a_i(y - z)) \mathbb{1}_{\{z < y\}} dz, \quad i \in \{0, 1\},$$

where  $a_0, a_1 > 0$  are constants, that is  $\hat{g}_i(\beta) = a_i / (a_i + \beta)$ . In this case we have

$$1 - \hat{g}_i(\beta) \Big|_{\beta = \frac{\lambda_i + s}{c_i}} = \frac{\beta}{a_i + \beta} \Big|_{\beta = \frac{\lambda_i + s}{c_i}} = \frac{\lambda_i + s}{\mu_i + s}, \quad i \in \{0, 1\},$$

where  $\mu_0 = a_0 c_0 + \lambda_0$ ,  $\mu_1 = a_1 c_1 + \lambda_1$ . Therefore

$$Q(s) = 1 - \frac{\lambda_0 \lambda_1}{(\mu_0 + s)(\mu_1 + s)} = \frac{q(s)}{(\mu_0 + s)(\mu_1 + s)}, \quad s > 0,$$



**Fig. 1.** Density functions  $f_0(0, 2, t)$  (absolutely continuous parts) with  $c_0 = 1, c_1 = 0.5$ : for (a)  $a_0 = a_1 = 1$ ;  $\lambda_0 = \lambda_1 = 1, 0.5, 0.2$  (from top to bottom); for (b)  $a_0 = a_1 = 1, 2, 5$ , respectively,  $\lambda_0 = \lambda_1 = 1, 0.5, 0.2$  (from top to bottom).

and (3.11) becomes

$$\begin{cases} \alpha_0(s) = \frac{a_0 c_0 s + \mu_1 a_0 c_0 + \lambda_0 a_1 c_1}{q(s)}, \\ \alpha_1(s) = \frac{a_1 c_1 s + \mu_0 a_1 c_1 + \lambda_1 a_0 c_0}{q(s)}, \end{cases} \tag{3.12}$$

where  $q(s) = (\mu_0 + s)(\mu_1 + s) - \lambda_0 \lambda_1, s > 0$ .

Let  $s_0^*$  and  $s_1^*$  be defined by  $q(s) = (s + s_0^*)(s + s_1^*)$ . It is easy to see that,  $s_0^*, s_1^* > 0$ , and

$$\alpha_i(s) = \frac{A_i}{s + s_0^*} + \frac{B_i}{s + s_1^*}, \quad i \in \{0, 1\},$$

where  $s_0^*, s_1^*$  are given by (3.4) and coefficients  $A_i, B_i, i \in \{0, 1\}$ , are defined by (3.5)–(3.6).

Making the inverse Laplace transformation we obtain functions  $h_0$  and  $h_1$ ,

$$h_0(t) = A_0 e^{-s_0^* t} + B_0 e^{-s_1^* t}, \quad h_1(t) = A_1 e^{-s_0^* t} + B_1 e^{-s_1^* t}, \quad t > 0. \tag{3.13}$$

By (3.8) and (3.13) the density functions of  $T_0^x(y)$  and  $T_1^x(y)$  are given by (3.3) (see Fig. 1).  $\square$

**Remark 3.1.** Formulae (3.8) give the solution of the problem for arbitrary distributions  $g_0$  and  $g_1$ : the density functions  $f_0$  and  $f_1$  are expressed by means of the inverse Laplace transforms  $h_0$  and  $h_1$  of  $\alpha_0$  and  $\alpha_1$ , (3.11).

**Example 3.1.** Let  $c_0 = c_1 = 1, \lambda_0 = \lambda_1 = \lambda$  and  $a_0 = a_1 = a$  (see Example 2.1). Then, by (3.3) we have

$$f_0 = f_1 = e^{-\lambda(y-x)} \delta(t - (y - x)) + \lambda a \cdot u(t \wedge (y - x), \lambda - a) e^{-at}.$$

**Remark 3.2.** The mean of the first passage time  $T^x(y)$  for a Markovian growth-collapse process has been studied in detail, see Löpker and Stadje (2011). Meanwhile, formula (3.3) presents the explicit representation of the distribution (in the special case of two-state processes with exponentially distributed jumps).

### 3.2. Velocities of opposite signs

Let the trends be of opposite signs,  $c = c_0 > 0 \geq c_1$ , and distributions  $g_0, g_1$  satisfy the condition  $g_i((-\infty, y)) = 1, i \in \{0, 1\}$ .

Since  $c_1 \leq 0$ , the distributions of  $T_0^x(y)$  and  $T_1^x(y), x < y$ , do not depend on  $g_1$  and  $c_1$ . Further,  $T_1^x(y)$  does not depend on the starting point  $x$ .

Let  $f_0(x, y, t)$  and  $f_1(y, t)$  be the density functions of distributions of  $T_0^x(y)$  and  $T_1^x(y)$  respectively.

**Theorem 3.2.** The first passage times  $T_0^x$  and  $T_1^x$  have proper distributions, (3.2).

Let the renewed starting point of the upwards movement be exponentially distributed,  $g_0(dx) \equiv g(dx) = a \exp(-a(y - x)) \mathbb{1}_{\{x < y\}} dx$ .

Then, the density functions  $f_0 = f_0(x, y, t)$  and  $f_1 = f(y, t) \equiv f_1(t)$  of  $T_0^x(y)$  and  $T_1^x(y)$  are given by the following:

$$f_0(x, y, t) = e^{-\lambda_0 \xi} \delta(t - \xi) + \frac{ac\lambda_0\lambda_1}{\sqrt{D}} \left[ u(t \wedge \xi, \lambda_0 - s_0^*) e^{-s_0^* t} - u(t \wedge \xi, \lambda_0 - s_1^*) e^{-s_1^* t} \right] \tag{3.14}$$

and

$$f_1(t) = \frac{ac\lambda_1}{\sqrt{D}} \left[ e^{-s_0^* t} - e^{-s_1^* t} \right], \quad t > 0, \tag{3.15}$$

where  $\xi = (y - x)/c$  and

$$s_0^* = \frac{1}{2}(\lambda_0 + \lambda_1 + ac - \sqrt{D}), \quad s_1^* = \frac{1}{2}(\lambda_0 + \lambda_1 + ac + \sqrt{D}), \quad 0 < s_0^* < s_1^*; \tag{3.16}$$

$$D = (\lambda_0 + \lambda_1 + ac)^2 - 4ac\lambda_1 = (\lambda_1 - ac)^2 + \lambda_0(\lambda_0 + 2\lambda_1 + 2ac)$$

and function  $u = u(\xi, \beta)$  is defined by (3.7).

By definitions (3.16) it turns out that  $\lambda_0 < s_1^*$  always holds. Further, the equality  $\lambda_0 = s_0^*$  holds, only if  $\lambda_0 = \frac{ac\lambda_1}{ac + \lambda_1}$ .

**Proof.** System (3.1) becomes

$$\begin{cases} f_0(x, y, t) = e^{-\lambda_0 \xi} \delta(t - \xi) + \int_0^{t \wedge \xi} \lambda_0 e^{-\lambda_0 \tau} f_1(y, t - \tau) d\tau, \\ f_1(y, t) = \int_0^t \lambda_1 e^{-\lambda_1 \tau} h(y, t - \tau) d\tau, \quad t > 0. \end{cases} \tag{3.17}$$

Here  $\xi = (y - x)/c$ ,  $c = c_0$ , and  $h(y, t) = \int_{-\infty}^{\infty} f_0(z, y, t) g(dz)$ , where  $g = g_0$  corresponds the distribution of the starting point of the upward motion.

Passing to the time-Laplace transform, we get

$$\begin{cases} [\mathcal{L}_{t \rightarrow s} f_0](x, y, s) = \exp(-(\lambda_0 + s)\xi) + \lambda_0 u(\xi, \lambda_0 + s) [\mathcal{L}_{t \rightarrow s} f_1](y, s), \\ [\mathcal{L}_{t \rightarrow s} f_1](y, s) = \frac{\lambda_1}{\lambda_1 + s} \alpha(y, s), \end{cases} \tag{3.18}$$

where

$$\alpha(y, s) = [\mathcal{L}_{t \rightarrow s} h](y, s) = \int_0^{\infty} e^{-st} \left[ \int_{-\infty}^{\infty} f_0(x, y, t) g(dx) \right] dt$$

is the time-Laplace transform of  $h$  and function  $u = u(\xi, \beta)$  is defined by (3.7).

Similarly to the proof of Theorem 3.1 one can obtain

$$\alpha(y, s) = \hat{g}((\lambda_0 + s)/c) + \frac{\lambda_0}{\lambda_0 + s} \left( 1 - \hat{g}((\lambda_0 + s)/c) \right) \frac{\lambda_1}{\lambda_1 + s} \alpha(y, s),$$

where  $\hat{g}(\beta) = \int_{-\infty}^{\infty} e^{-\beta(y-x)} g(dx)$ . Therefore

$$\alpha(y, s) = \frac{\hat{g}((\lambda_0 + s)/c)}{1 - \frac{\lambda_0\lambda_1}{(\lambda_0+s)(\lambda_1+s)} \left( 1 - \hat{g}((\lambda_0 + s)/c) \right)}. \tag{3.19}$$

If the distribution of the renewed starting point is exponential,  $g(dx) = a \exp(-a(y - x)) \mathbb{1}_{\{x < y\}} dx$ , that is  $\hat{g} \left( \frac{\lambda_0 + s}{c} \right) = \int_{-\infty}^y \exp \left( -(\lambda_0 + s) \frac{y-x}{c} \right) g(dx) = \frac{ac}{ac + \lambda_0 + s}$ , then (3.19) becomes

$$\alpha = \frac{ac(\lambda_1 + s)}{q(s)},$$

where  $q(s) = (ac + \lambda_0 + s)(\lambda_1 + s) - \lambda_0\lambda_1 = s^2 + (\lambda_0 + \lambda_1 + ac)s + ac\lambda_1 = (s + s_0^*)(s + s_1^*)$  with  $s_0^*$  and  $s_1^*$  given by (3.16). Hence,

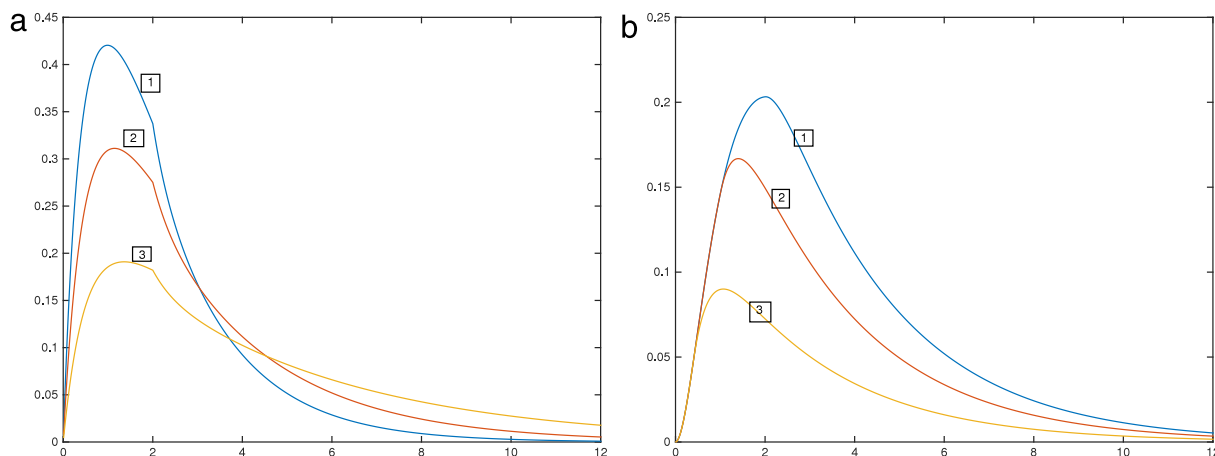
$$\alpha = \frac{ac}{\sqrt{D}} \left[ \frac{\lambda_1 - s_0^*}{s + s_0^*} + \frac{s_1^* - \lambda_1}{s + s_1^*} \right],$$

and the inverse Laplace transform  $h$  can be expressed by

$$h \equiv \frac{ac}{\sqrt{D}} \left[ (\lambda_1 - s_0^*) e^{-s_0^* t} - (\lambda_1 - s_1^*) e^{-s_1^* t} \right].$$

With this in hand, due to the second equation of (3.17) we easily obtain (3.15). Then, by the first equation of (3.17) one can obtain (3.14). See Fig. 2.  $\square$





**Fig. 2.** Density functions  $f_0(0, 2, t)$  (absolutely continuous parts) with  $c = c_0 > 0 > c_1$ : for (a) with  $c = 1, a = 1, \lambda_0 = 1$  and  $\lambda_1 = 2, 1; \lambda_1 = 1, 2; \lambda_1 = 0.5, 3$ ; for (b) with  $\lambda_0 = \lambda_1 = 1$  and  $c = 1, a = 1, 1; c = 2, a = 0.5, 2; c = 5, a = 0.2, 3$ .

**Remark 3.3.** The distribution  $\bar{f} = \bar{f}(t)$  of the times between consequent passages through the fixed level  $y$  satisfies the equation

$$\bar{f}(t) = \int_0^t \lambda_0 e^{-\lambda_0 \tau} f_1(t - \tau) d\tau.$$

By (3.15)

$$\begin{aligned} \bar{f}(t) &= \frac{\lambda_0 \lambda_1 a c}{\sqrt{D}} \int_0^t e^{-\lambda_0 \tau} \left[ e^{-s_0^*(t-\tau)} - e^{-s_1^*(t-\tau)} \right] d\tau \\ &= \frac{\lambda_0 \lambda_1 a c}{\sqrt{D}} \left[ u(t, \lambda_0 - s_0^*) e^{-s_0^* t} - u(t, \lambda_0 - s_1^*) e^{-s_1^* t} \right]. \end{aligned}$$

**4. Conclusion**

Distributions of a piecewise linear process which starts after each tendency switching from a new random point are completely described. In the case of two-state process the distributions of the level passage time are presented explicitly. Applications of these processes will be presented elsewhere later.

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